

# Default Reasoning on Top of Ontologies with dl-Programs

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# Outline

## 1 Motivating Example

## 2 Introduction

- Default Logic at a glance
- An overview of dl-programs
- From Default Logic to dl-programs

## 3 Transformations

- Some conventions
- Select-defaults-and-check based transformations
- Select-justifications-and-check based transformation

## 4 Experimental Results

- Transformation  $\Pi$
- Transformation  $\Omega$
- Transformation  $\Upsilon$
- Compare 3 transformations in caching mode

## 5 Conclusions and Future work

- Simple bird ontology
  - $Flier \sqsubseteq \neg NonFlier$
  - $Penguin \sqsubseteq Bird$
  - $Penguin \sqsubseteq NonFlier$
  - $Penguin(tweety)$
  - $Bird(joe)$
- How to enable *default reasoning* on top of ontologies?
- First attempt to embed default reasoning into terminological knowledge representation by Baader (1993)
- Integration of rules and ontologies

- One of the most famous nonmonotonic reasoning formalizations.
- Default rules: 
$$\frac{\alpha(\vec{X}) : \beta_1(\vec{X}), \dots, \beta_m(\vec{X})}{\gamma(\vec{X})}$$
- Default theory:  $T = \langle W, D \rangle$ .
- The totality of knowledge induced by a default theory: **extension**.
- Our purpose: allow each  $\alpha, \beta, \gamma$  to be either a concept or a role name in a DL-KB. For instance:

$$\frac{Bird(X) : Flier(X)}{Flier(X)}$$

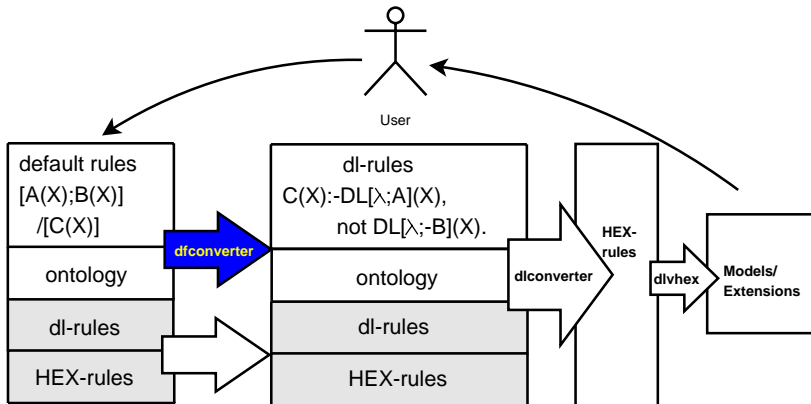
- Theoretical point of view:

- an approach on the integration of rules and ontologies
- key idea: DL atoms which allow us to **update** and **query** the DL-KB

Eg:

$$\text{DL}[\underbrace{\text{WhiteWine} \uplus \text{iswhitewhine}}_{\text{input list for updating}}; \underbrace{\neg \text{WhiteWine}}_{\text{query}}](X).$$

- strict semantics integration
- Practical point of view:
  - dlhex: a prover for Semantics Web Reasoning under Answer-Set Semantics, available with a plugin environment
  - dlhex-dlplugin: allows the use of DL atoms, communicates with a DL-KB via RacerPro



- Default theory  $\Delta = \langle L, D \rangle$ ;  $L$  is a DL knowledge base,  
 $D \equiv \{\delta_1, \dots, \delta_n\}$
- $\delta \equiv \frac{\alpha(\vec{X}); \beta_1(\vec{Y}_1), \dots, \beta_m(\vec{Y}_m)}{\gamma(\vec{Z})}$
- $name(\gamma)$ : **predicate name** of the literal  $\gamma$
- $aux_\gamma$ :
  - $in\_name(\gamma)$  if  $\gamma$  is positive
  - $in\_not\_name(\gamma)$  if  $\gamma$  is negative
- $auxc_{\beta_i}$ :
  - $cons\_name(\beta_i)$  if  $\beta_i$  is positive
  - $cons\_not\_name(\beta_i)$  if  $\beta_i$  is negative

# Transformation $\Pi$

- Rules that guess whether  $\delta$ 's conclusion belongs to the extension  $E$ :

$$aux\_g(\vec{Z}) \leftarrow \text{not } out\_aux\_g(\vec{Z}).$$

$$out\_aux\_g(\vec{Z}) \leftarrow \text{not } aux\_g(\vec{Z}).$$

- A rule that checks the compliance of the guess for  $E$  with  $L$   
 $fail \leftarrow DL[\lambda'; \gamma](\vec{Z}), out\_aux\_g_i(\vec{Z}), \text{not } fail.$

$$\text{where } \lambda' \equiv \bigcup_{\delta_i \in D} (\gamma_i \uplus in\_name(\gamma_i); \gamma_i \uplus in\_not\_name(\gamma_i))$$

- A rule for applying  $\delta$  as in  $\Gamma_{\Delta}(E)$

$$p\_aux\_g(\vec{Z}) \leftarrow DL[\lambda; \alpha](\vec{X}),$$

$$\text{not } DL[\lambda; \neg\beta_1](\vec{Y}_1), \dots, \text{not } DL[\lambda; \neg\beta_m](\vec{Y}_m).$$

$$\text{where } \lambda \equiv \bigcup_{\delta_i \in D} (\gamma_i \uplus p\_in\_name(\gamma_i); \gamma_i \uplus p\_in\_not\_name(\gamma_i))$$



# Transformation $\Pi$ - cont.

- Rules which check whether  $E$  and  $\Gamma_{\Delta}(E)$  coincide:

*fail*  $\leftarrow$  not  $DL[\lambda; \gamma](\vec{Z}), aux_{\gamma}(\vec{Z}),$  not *fail*.

*fail*  $\leftarrow DL[\lambda; \gamma](\vec{Z}), out_{aux_{\gamma}}(\vec{Z}),$  not *fail*.

- Idea: a 2-phase process
  - Phase 1: guessing whether defaults' conclusions belong to the extension ( $\lambda'$ )
  - Phase 2: applying defaults and check if  $E$  and  $\Gamma_{\Delta}(E)$  coincide ( $\lambda$ )

# Transformation $\Omega$

- Idea: exploit the guessing phase of ASP, the condition for an interpretation to be an answer set
- hence we need to specify only one rule for each default:
- $aux\_ \gamma(\vec{Z}) \leftarrow DL[\lambda; \alpha](\vec{X}),$   
 $\text{not } DL[\lambda; \neg\beta_1](\vec{Y}_1), \dots, \text{not } DL[\lambda; \neg\beta_m](\vec{Y}_m).$

where:

$$\lambda = \bigcup_{\delta_i \in D} (\gamma_i \uplus in\_name(\gamma_i), \gamma_i \uplus in\_not\_name(\gamma_i))$$

# The algorithm

1. Select a set of justifications  $J \subseteq j(D)$
2. Find the set of defaults  $S$  whose justifications belong to  $J$
3. Compute the set of consequences  $E$  of  $W$  that can be derived by means of defaults in  $S$  (a default fires if its prerequisite has been derived earlier).
4. If all justifications in  $J$  are consistent with  $E$  and every default not in  $S$  has at least one justification not consistent with  $E$ , the output  $E$  as an extension.
5. Repeat until all subsets of  $j(D)$  are considered or pruned.

# Transformation $\Upsilon$

- Rules that select justifications:

$$auxc_{\beta_i}(\vec{Y}_i) \leftarrow \text{not } out\_auxc_{\beta_i}(\vec{Y}_i).$$

$$out\_auxc_{\beta_i}(\vec{Y}_i) \leftarrow \text{not } auxc_{\beta_i}(\vec{Y}_i).$$

- A rule which computes the set of consequences  $E$ :

$$aux_{\gamma}(\vec{Z}) \leftarrow DL[\lambda; \alpha](\vec{X}), auxc_{\beta_1}(\vec{Y}_1), \dots, auxc_{\beta_m}(\vec{Y}_m).$$

where:

$$\lambda = \bigcup_{\delta_i \in D} (\gamma_i \uplus in\_name(\gamma_i), \gamma_i \uplus in\_not\_name(\gamma_i))$$

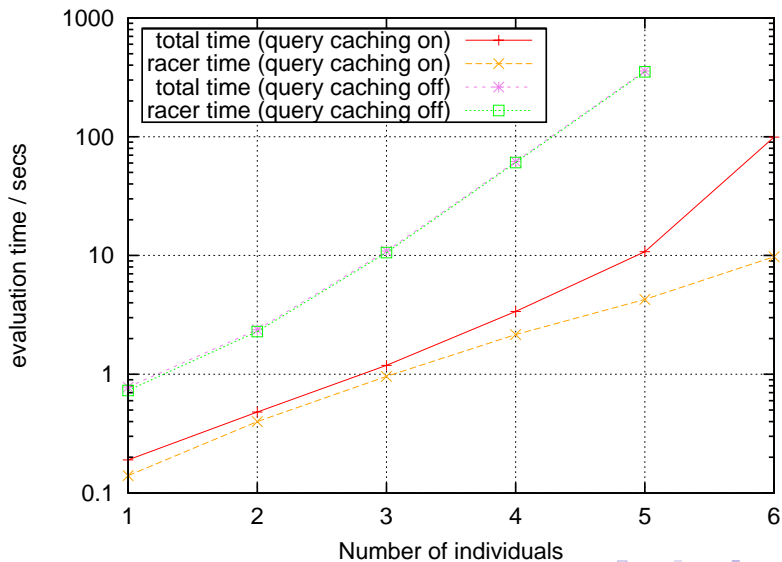
Transformation  $\Upsilon$  - cont.

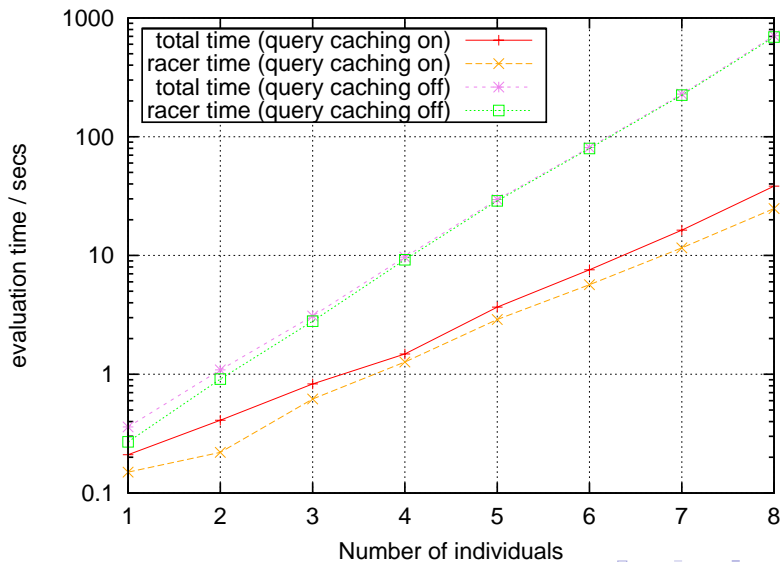
- Rules that check the compliance of our guess with E

$fail \leftarrow DL[\lambda; \neg\beta_i](\vec{Y}_i), auxc\_beta_i(\vec{Y}_i), \text{ not } fail.$

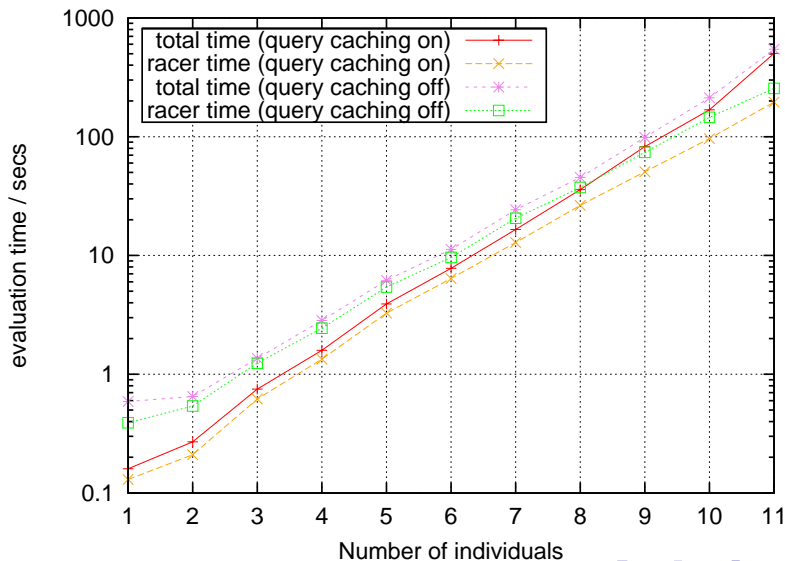
$fail \leftarrow \text{ not } DL[\lambda; \neg\beta_i](\vec{Y}_i), out\_auxc\_beta_i(\vec{Y}_i), \text{ not } fail.$

- 3 transformations were tested under different examples: Tweety bird, Nixon Diamond, Small Wine, etc., and two running modes, namely using caching and not
- Criteria to compare: total running time, RacerPro's time and dlhex time
- We show the result of the Tweety bird example

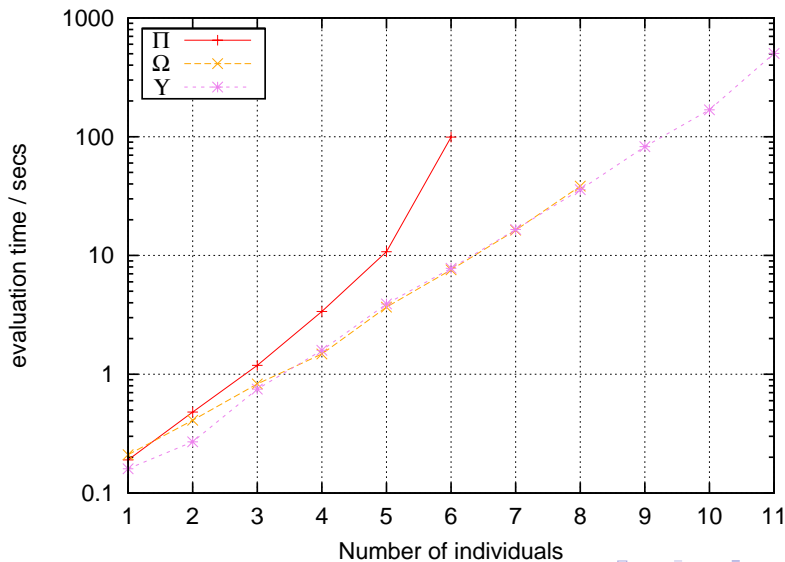
Transformation  $\Pi$ 

Transformation  $\Omega$ 



Transformation  $\Upsilon$ 

Compare 3 transformations in caching mode



## ■ Conclusions:

- Three transformations work correctly
- $\Omega$  and  $\Upsilon$  are much faster than  $\Pi$
- Caching technique concerning calls to ontologies plays an important role in improving the system's performance

## ■ Future work:

- Investigate more pruning rules
- Upgrade `dlvhex` for pruning rules to take effect
- Investigate transformations for special default theories such as normal default, semi-normal default
- Implement caching for cq-programs in the `dl-plugin`
- Interface to different DL-reasoners, eg., Pellet, KAON2
- Explore the possibility of classifying the input to reduce the search space