

# Distributed Nonmonotonic Multi-Context Systems

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# Overview

Multi-Context Systems

Distributed Algorithm for Evaluating Nonmonotonic MCS

Loop Formulas for Multi-Context Systems

Experiments

Conclusions

# Multi-Context Systems (MCS)

- ▶ MCSen introduced by [Giunchiglia and Serafini, 1994]:
  - ▶ represent inter-contextual information flow
  - ▶ express reasoning w.r.t. contextual information
  - ▶ allow decentralized, pointwise information exchange
  - ▶ monotonic, homogeneous logic
- ▶ Framework extended for integrating **heterogeneous and nonmonotonic logics** [Brewka and Eiter, 2007]

# Syntax of Multi-Context Systems

- ▶ multi-context system
  - ▶ a collection  $M = (C_1, \dots, C_n)$  of contexts
- ▶ context  $C_i = (L_i, kb_i, br_i)$ 
  - ▶  $L_i$ : a logic
  - ▶  $kb_i$ : a knowledge base of logic  $L_i$
  - ▶  $br_i$ : a set of bridge rules

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  - ▶  $br_i$ : a set of bridge rules
- ▶ logic  $L = (\mathbf{KB}_L, \mathbf{BS}_L, \mathbf{ACC}_L)$ 
  - ▶  $\mathbf{KB}_L$ : set of well-formed knowledge bases
  - ▶  $\mathbf{BS}_L$ : is the set of possible belief sets
  - ▶  $\mathbf{ACC}_L$ : acceptability function  $\mathbf{KB}_L \mapsto 2^{\mathbf{BS}_L}$   
Which belief sets are accepted by a knowledge base?

## Semantics of Multi-Context Systems (2)

- ▶ *multi-context system*

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# Syntax of Multi-Context Systems (bridge rules)

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- ▶ *logic*

$$L_i = (\mathbf{KB}_i, \mathbf{BS}_i, \mathbf{ACC}_i)$$

- ▶ **Bridge rule**  $r \in br_i$  of a context  $C_i$

$$s \leftarrow (c_1 : p_1), \dots, (c_j : p_j), \\ \text{not } (c_{j+1} : p_{j+1}), \dots, \text{not } (c_m : p_m)$$

- ▶  $(c_k : p_k)$  looks at belief  $p_k$  in context  $C_{c_k}$
- ▶  $r$  is applicable  $:\Leftrightarrow$  positive/negative beliefs are present/absent
- ▶ we add the head  $s$  to  $kb_i$  if  $r$  is applicable

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- ▶ *knowledge base of a context  $C_i$*

$$kb_i \in \mathbf{KB}_i$$

- ▶ *set of bridge rules  $br_i$  of a context  $C_i$  of form*

$$s \leftarrow (c_1 : p_1), \dots, (c_j : p_j), \text{not } (c_{j+1} : p_{j+1}), \dots, \text{not } (c_m : p_m)$$

- ▶ Contexts  $C_1, \dots, C_n$  are knowledge bases with semantics in terms of **accepted belief sets**

- ▶  $S = (S_1, \dots, S_n)$  is a **belief state** of  $M$  with each  $S_i \in \mathbf{BS}_i$



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- ▶ **Equilibrium semantics**

- ▶ A belief state  $S = (S_1, \dots, S_n)$  with  $S_i \in \mathbf{BS}_i$   
... makes certain bridge rules applicable,  
... add applicable bridge heads to  $kb_i$

$\Rightarrow$   $S$  is an equilibrium  $:\Leftrightarrow$

each  $kb_i$  plus acceptable bridge heads from  $br_i$  accepts  $S_i$

$$S_i \in \mathbf{ACC}_i(kb_i \cup \{head(r) \mid r \in app(br_i, S)\})$$

# Toward Distributed Equilibria building for MCS

## Obstacles:

- ▶ abstraction of contexts
- ▶ information hiding and security aspects
- ▶ lack of system topology
- ▶ cycles between contexts

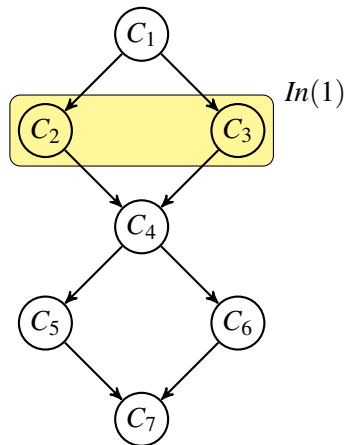
## We need to capture:

- ▶ dependencies between contexts
- ▶ representation of partial knowledge
- ▶ combination/join of local results

# Import Closure

Import neighborhood of  $C_k$

$$In(k) = \{c_i \mid (c_i : p_i) \in B(r), r \in br_k\}$$



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Import closure  $IC(k)$  of  $C_k$  is the smallest set  $S$  such that

(i)  $k \in S$  and

(ii) for all  $i \in S$ ,  $In(i) \subseteq S$ .

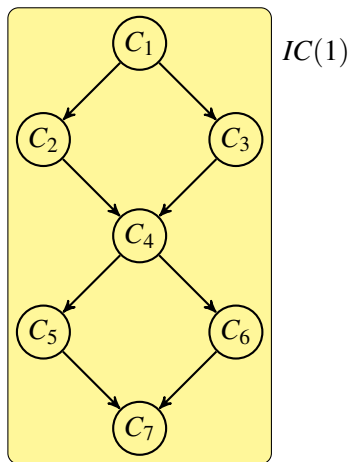
Alternatively,

$$IC(k) = \{k\} \cup \bigcup_{j \geq 0} IC^j(k) ,$$

where

$$IC^0(k) = In(k), \text{ and}$$

$$IC^{j+1}(k) = \bigcup_{i \in IC^j(k)} In(i).$$



## Partial Belief States and Equilibria

Let  $M = (C_1, \dots, C_n)$  be an MCS, and let  $\epsilon \notin \bigcup_{i=1}^n \mathbf{BS}_i$

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$S = (S_1, \dots, S_n)$  is a **partial equilibrium** of  $M$  w.r.t. a context  $C_k$  iff for  $1 \leq i \leq n$ ,

- ▶ if  $i \in IC(k)$  then  $S_i \in \mathbf{ACC}_i(kb_i \cup \{head(r) \mid r \in app(br_i, S)\})$
- ▶ otherwise,  $S_i = \epsilon$

## Joining Partial Belief States

Join  $S \bowtie T$  of belief sets  $S$  and  $T$ : like join of tuples in a database.

$$S = \begin{array}{|c|c|c|c|c|c|c|} \hline S_1 & \dots & \epsilon & \dots & \epsilon & \dots & S_n \\ \hline \end{array}$$

$$T = \begin{array}{|c|c|c|c|c|c|c|} \hline \epsilon & \dots & \epsilon & \dots & T_i & \dots & T_n \\ \hline \end{array}$$

$$S \bowtie T = \begin{array}{|c|c|c|c|c|c|c|} \hline S_1 & \dots & \epsilon & \dots & T_i & \dots & S_n = T_n \\ \hline \end{array}$$

$S \bowtie T$  is undefined, if  $\epsilon \neq S_j \neq T_j \neq \epsilon$  for some  $j$ .

$$S \bowtie T = \{S \bowtie T \mid S \in \mathcal{S}, T \in \mathcal{T}\}$$



## Algorithm DMCS

**Input:** an MCS  $M$  and a starting context  $C_k$

**Output:** all partial equilibria of  $M$  w.r.t.  $C_k$

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Input parameters for DMCS:

- ▶  $V$ : set of “interesting” variables (to project the partial equilibria)
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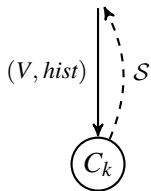
Strategy: DFS-traversal of  $M$  starting with  $C_k$ , visiting all  $C_i$  for  $i \in IC(k)$

Instances of DMCS

- ▶ running at each context node,
- ▶ communicating with each other for exchanging sets of belief states

## Acyclic case

Leaf context  $C_k$  ( $br_k = \emptyset$ )

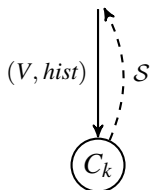


$$\text{Isolve}((\epsilon, \dots, \epsilon)) = \mathcal{S}$$

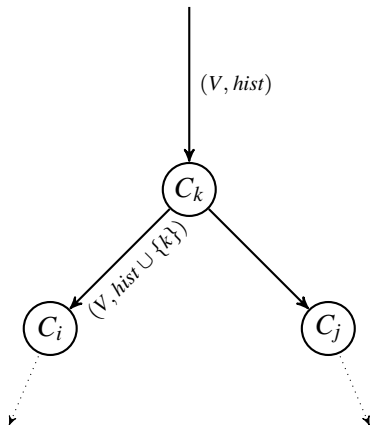
## Acyclic case

Intermediate context  $C_k$   
 $((i : p), (j : q))$  appear in  $br_k$

Leaf context  $C_k$  ( $br_k = \emptyset$ )



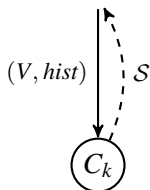
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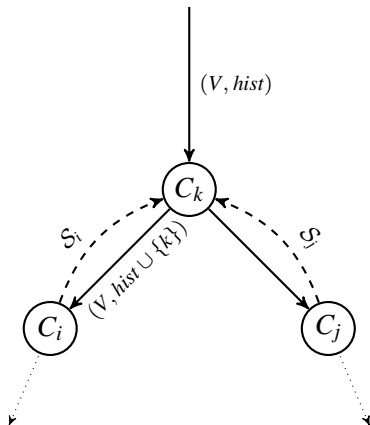
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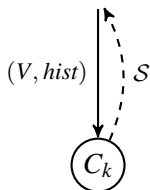
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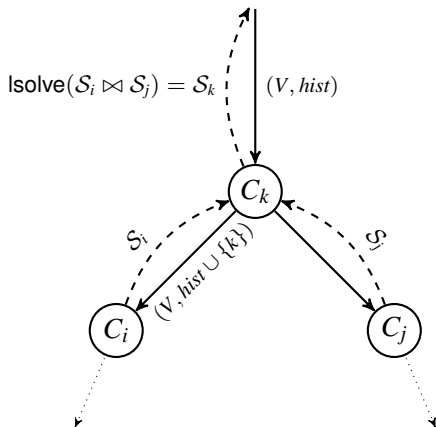
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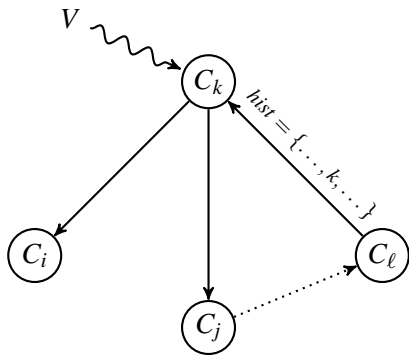
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$$\text{Isolve}(\mathcal{S}_i \bowtie \mathcal{S}_j) = \mathcal{S}_k \quad (V, hist)$$

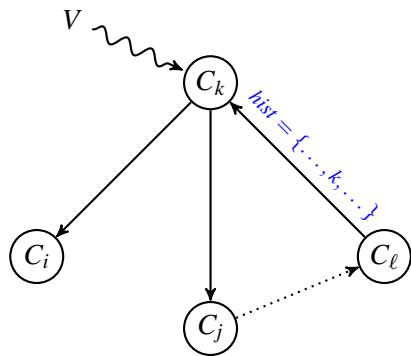


# Cycle breaking



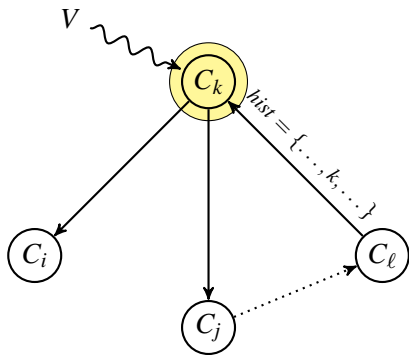
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$C_k$  detects a cycle in *hist*



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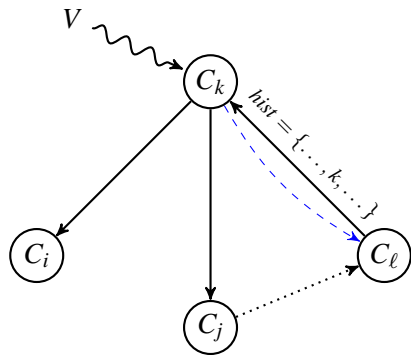
$C_k$  detects a cycle in *hist*



► **Guessing** local belief sets

# Cycle breaking

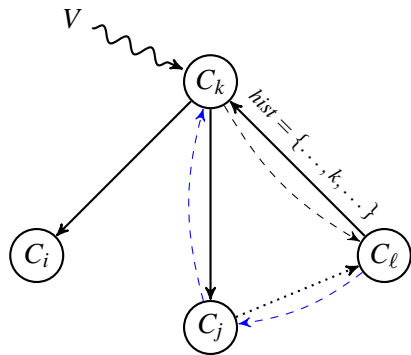
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- ▶ Guessing local belief sets
- ▶ **return** them to invoking context

# Cycle breaking

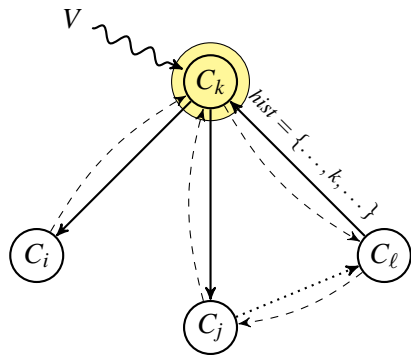
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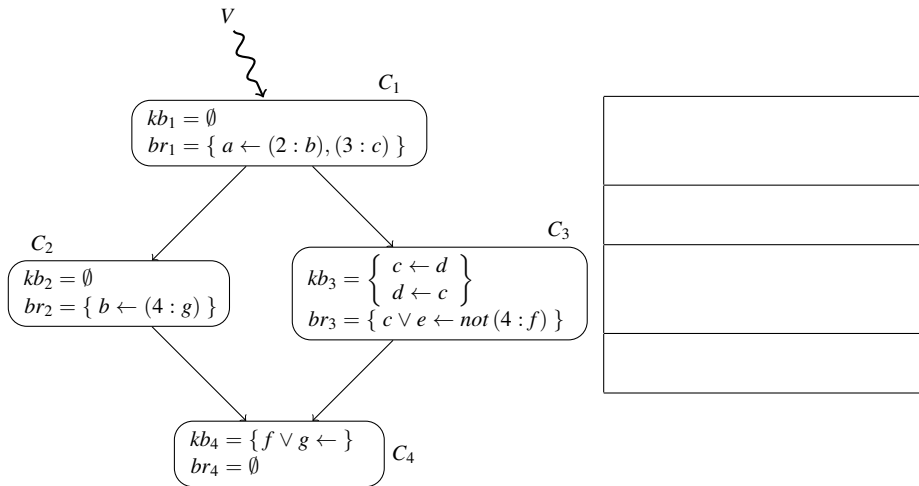
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- ▶ Guessing local belief sets
- ▶ return them to invoking context
- ▶ on the way back, partial belief states w.r.t. bad guesses will be pruned by  $\boxtimes$
- ▶ eventually,  $C_k$  will remove wrong guesses by calling **lsolve** on each received partial belief state

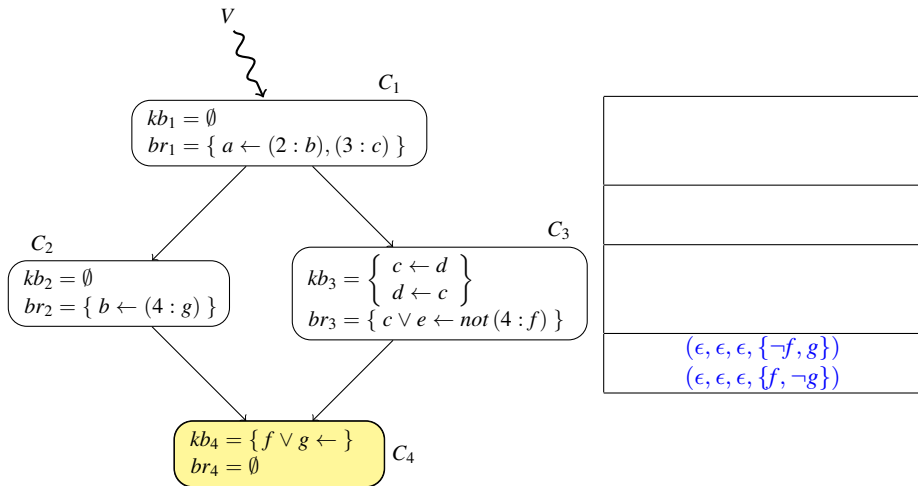
## Example

A run with  $C_1.DMCS(V, \emptyset)$ , where  $V = \{a, b, c, f, g\}$ .



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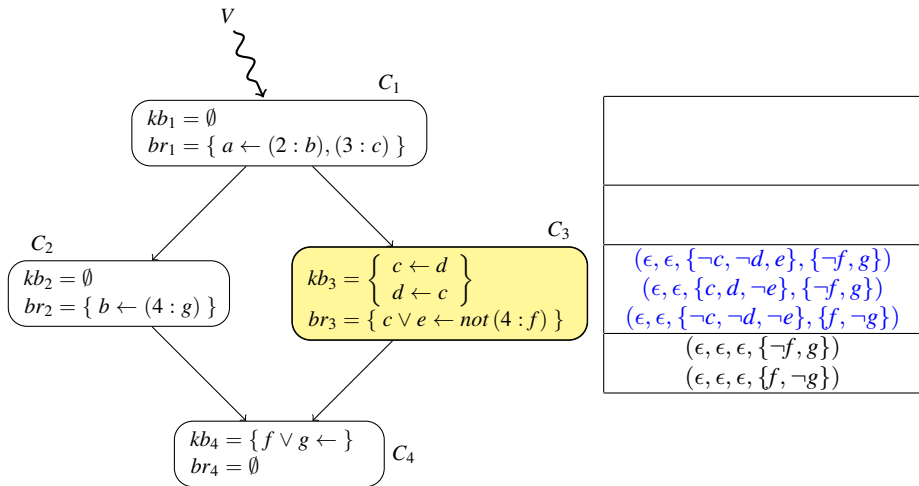
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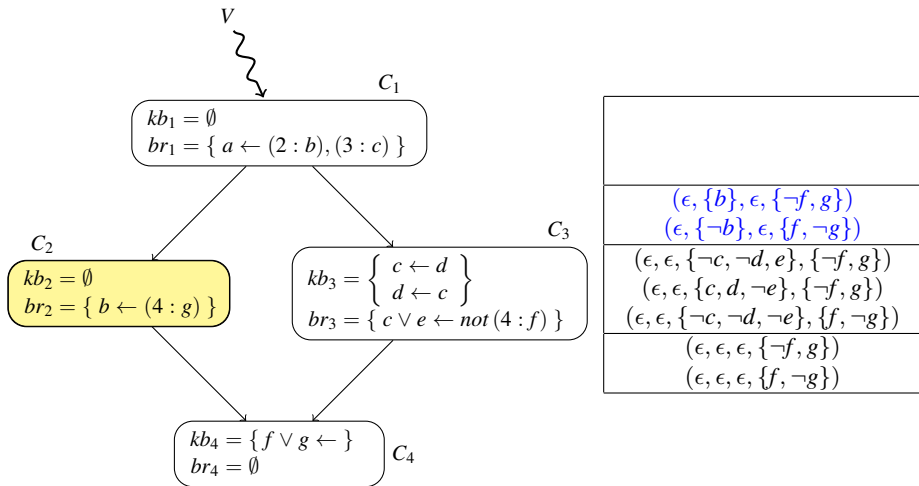
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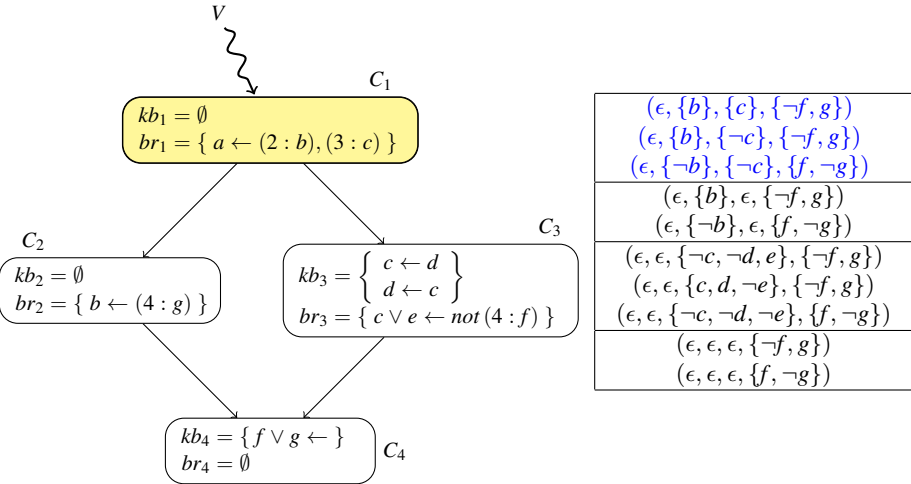
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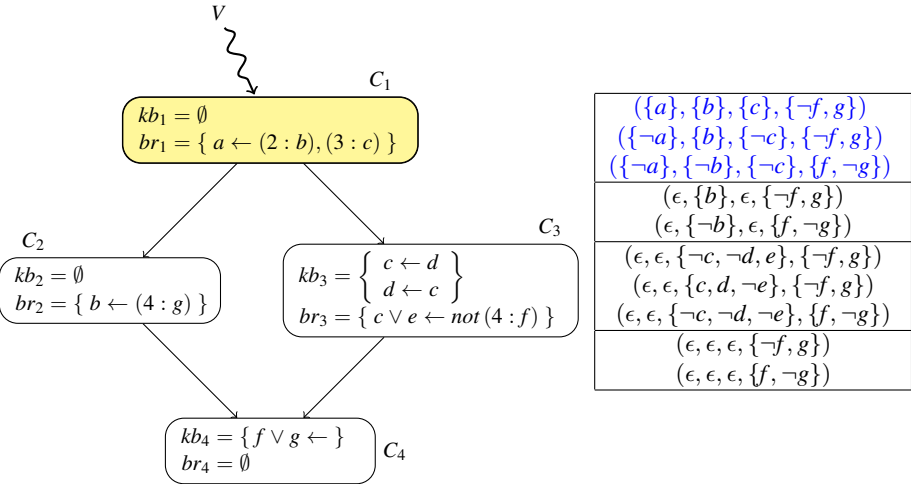
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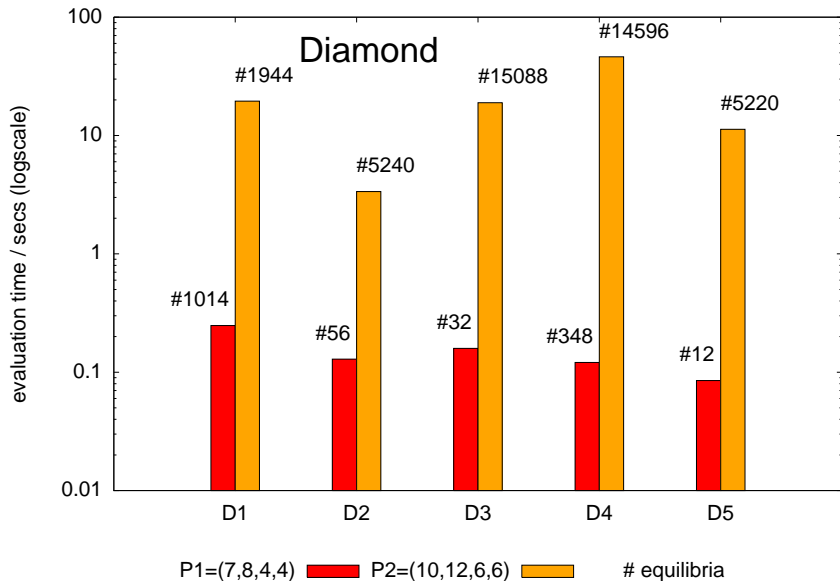
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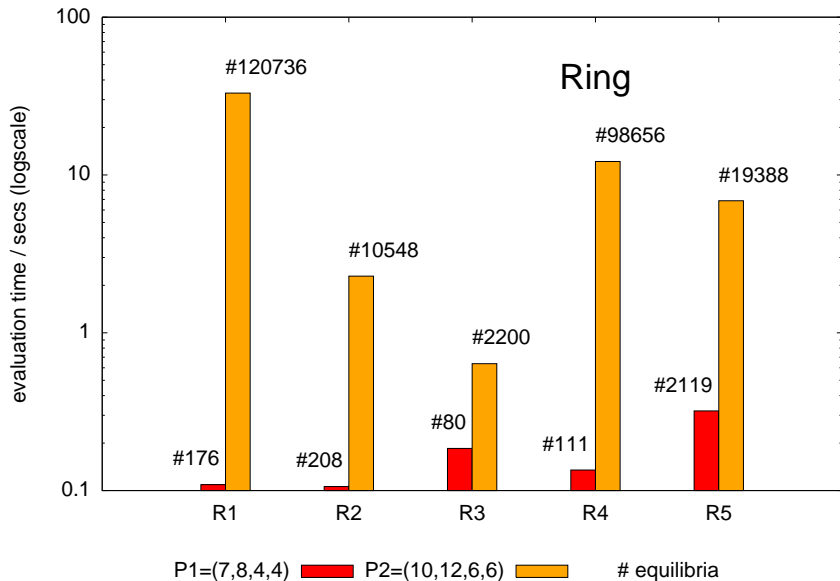
# Loop Formulas for Multi-Context Systems

- ▶ DMCS is using `Isolve()` to incorporate the bridge rules into the local knowledge base: this must be done for every intermediate result
- ▶ Some logics allow to combine  $br_i$  and  $kb_i$ :
  - ▶ contexts with answer set programs, or
  - ▶ contexts with propositional formulas
- ▶ Benefit: a single call to a SAT solver is sufficient to compute the local semantics of a context
- ▶ This is used to adapt DMCS and provide a prototype implementation

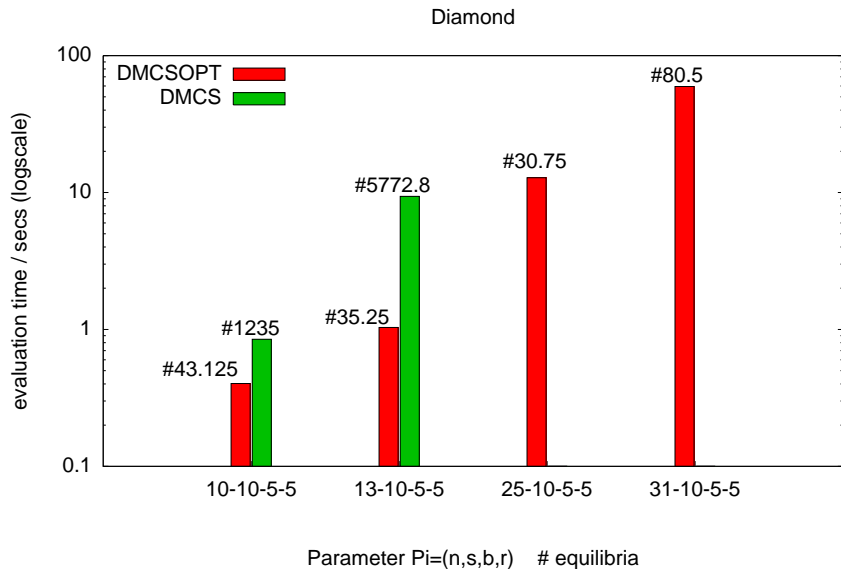
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## Conclusions

- ▶ MCS is a general framework for integrating diverse formalisms
- ▶ First attempt for distributed MCS evaluation
- ▶ In certain settings, we can compile bridge rules away and use SAT solvers locally to generate partial equilibria (loop formulas for MCS)
- ▶ Initial experiments with a prototype implementation

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## Future work:

- ▶ improve scalability
  - ▶ move away from “knowing-nothing” to “knowing-something”
  - ▶ approximation semantics
  - ▶ syntactic restrictions
  - ▶ specialized algorithms for some types of topologies
- ▶ how to deal with dynamic setting?

# Related work

## Frameworks/Platforms

- ▶ Framework for P2P inference systems [Hirayama and Yokoo, 2005]: consequence finding v.s. model building
- ▶ MWeb [Analyti *et al.*, 2008]: scope and context for modular web rule bases on the Web

## Distributed Reasoning

- ▶ Satisfiability checking for homogeneous, monotonic MCS [Roelofsen *et al.*, 2004]: (co-inductive) fixpoint strategy, not truly distributed
- ▶ DisSAT [Hirayama and Yokoo, 2005]: finding single models (randomize)
- ▶ Distributed Description Logic [Serafini and Tamilin, 2005], [Serafini *et al.*, 2005]
  - ▶ reasoning v.s. (distributed) model building
  - ▶ loose v.s. tight integration (signatures, meaning of symbols)

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