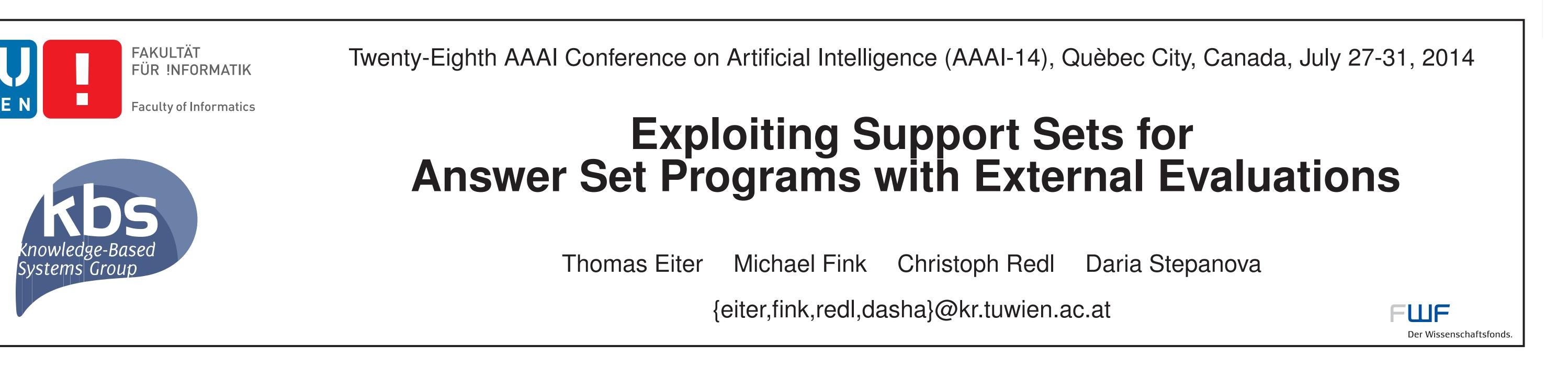
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| 1. Motivation | 3. Using Support Sets |
|---------------|-----------------------|
|---------------|-----------------------|

- HEX-programs extend ASP by external sources
- DL-program $\Pi = \langle \mathcal{O}, P \rangle$, ontology+rules (special case of HEX-programs)



- Standard HEX-Program Evaluation:
 - From Π construct $\hat{\Pi}$ with all external *a* substituted by e_a
- Add $e_a \lor ne_a$ to $\hat{\Pi}$, where ne_a corresponds to negation of e_a For each $\hat{A} \in AS(\hat{\Pi})$, check compatibility (i.e. $Te_a \in \hat{A}$ iff $A \models a$?) and minimality (i.e. exclude self-support)

 $\mathcal{O} = \left\{ \begin{array}{l} (1) \ Driver \sqsubseteq \neg Customer \ (4) \ worksIn(d1, r3) \\ (2) \ \exists .worksIn \sqsubseteq Driver \ (5) \ worksIn(d1, r4) \\ (3) \ ECarDriver \sqsubseteq Driver \ (6) \ ECarDriver(d1) \end{array} \right\}$

(6) isIn(c1, r2); (7) isIn(d1, r2); (8) needsTo(c1, r3) (9) goTo(d1, r4); (10) $cust(X) \leftarrow isIn(X, Y), not DL[worksIn \uplus goTo; \neg Customer](X);$ (11) $driver(X) \leftarrow not customer(X), isIn(X, Y);$ $P = \langle (12) drives(X, Y) \leftarrow driver(X), customer(Y), isIn(X, Z), \rangle$ isIn(Y,Z), not omit(X,Y);(13) $omit(X, Y) \leftarrow needsTo(Y, Z), not DL[; worksIn](X, Z),$ $drives(X, Y), DL[Driver \uplus driver; ECarDriver](X)$

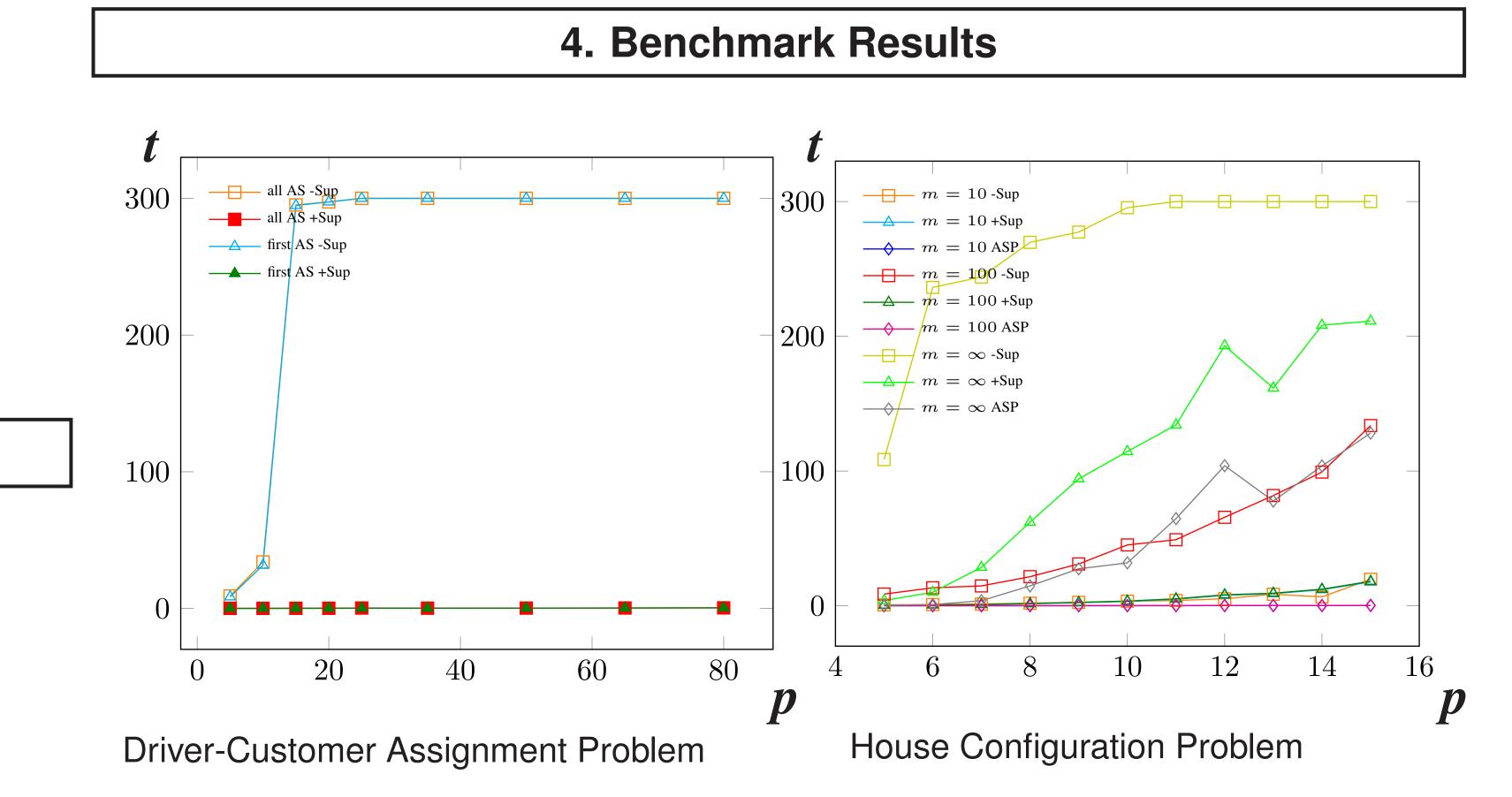


- Aim of this work: avoid multiple calls
- Contributions:
 - (Non-)ground support sets as optimization means
 - Application examples:
 - ▶ DL-programs (*DL-Lite*_A) and



New Approach:

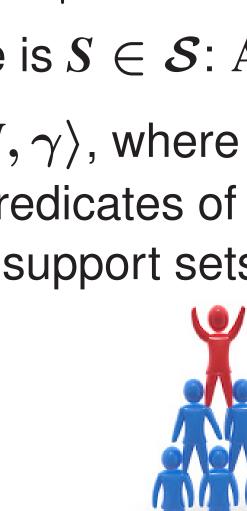
- ▶ Support Sets in AS Search: for $S \in S^+(a)$ (resp. $S \in S^-(a)$) adding $S \cup \{Fe_a\}$ (resp. $S \cup \{Te_a\}$) to Π prunes not compatible A
- Compatibility Check: with complete support families for all a of Π external source accesses can be fully eliminated
- Support sets must be small and easily computable!
- ▶ DL-programs over consistent DL-Lite_A ontologies:
 - ▶ size is at most 2
 - computation is tractable
- Also: QA over positive ASP (e.g. subproblems)



- Query Answering (QA) over ASP
- Implementation in DLVHEX and experiments

2. Support Sets

- Support Sets encode partial info about external source
- Ground Support Set for $a = DL[worksIn \ \uplus \ goTo; \neg Cust](d1)$: $S = \{TgoTo(d_1, r4)\}$ for all assignments $A \supseteq S$: $A \models a$
- ▶ Complete Support Family S for a: for all A there is $S \in S$: A $\supset S$
- Nonground Support Set S for a(X) is of form $\langle N, \gamma \rangle$, where \triangleright N: set of signed nonground literals over input predicates of a(X)
 - $\sim \gamma$: function, selecting groundings of N, that are support sets for a(c)
- $S_1 = \langle \{TgoTo(X, X')\}, \top \rangle$, where \top returns 1 for all groundings of **T***goTo*(*X*, *X'*)
- $S_2 = \langle \emptyset, \gamma \rangle$, where



- t: time in seconds, p: size of instance
- m: bound on number of computed AS
- +Sup (-Sup): using support sets (resp. standard computation)
- first (all) AS: computing first (resp. all) answer sets

Other benchmarks:

 $\gamma: \mathcal{C} \times \{\emptyset\} \to \{0,1\}$ is s.t. $\gamma(c, \emptyset) = 1$ iff $EDriver(c) \in \mathcal{A}$ of \mathcal{O}

- Default rules over university LUBM ontology
- Graph non-3-colorability problem

5. Conclusion and Outlook

Results:

- Support sets are viewed as knowledge compilation
- Experimental results show significant improvements for practical applications: DL-programs over DL-Lite_A and QA over positive ASP
- Calvanese, D.; Lembo, D.; Lenzerini, M.; and Rosati, R.

Tractable reasoning and efficient query answering in description logics: The DL-Lite family. Journal of Automated Reasoning, 2007, 39(3):385–429.

Future work:

- Sophisticated algorithms for nogood grounding, coverage checking
- Exploiting info about the program by support sets
- Further optimization techniques
- ► Eiter, T.; Fink, M.; Krennwallner, T.; Redl, C.; and Schüller, P. Efficient HEX-program evaluation based on unfounded sets. Journal of Artificial Intelligence Research, volume 49, pages 269-321, February 2014.